

Coffee Can Radar System

Dale Coker & Kyle Meza

Advisor – Prof. Pappu & Dr. Silva

Background:

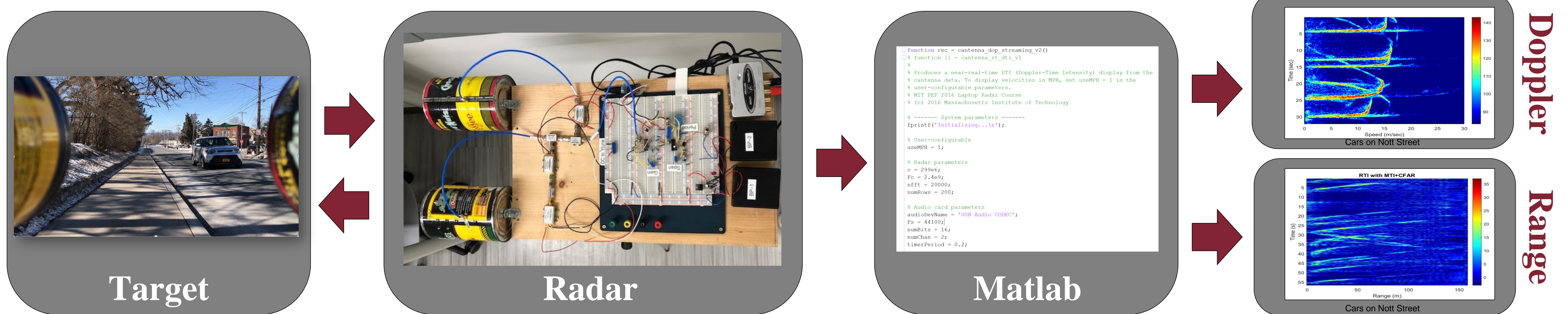
- **Radio Detection and Ranging** uses electromagnetic waves to detect and extract target information
- Delay and Doppler can be extracted from received signal
- Delay = time for signal to reach target and return = τ
- Doppler = frequency shift of received signal vs. transmitted signal = F_D

Key Equations

Doppler:
 Transmit Monotone: $s(t) = A \cos(2\pi F_c t + \theta)$ $F_c = 2.45 \text{ GHz}$
 Mixer Output $m(t) = A' \cos(2\pi F_d t + \theta')$ $F_d = 245 \text{ Hz}$
 Velocity = $\frac{\lambda F_d}{2} = 33.5 \text{ MPH}$
 Range:
 Transmit Linear FM = $A \cos(2\pi F_c t + \pi K t^2 + \theta)$; $K = 5 \text{ GHz/sec}$
 Mixer Output $m(t) = A' \cos(2\pi K t + \theta')$ $\text{Freq. shift} = 3 \text{ kHz}$ $\therefore \tau = 0.6 \mu\text{sec}$
 Range = $\frac{c\tau}{2} = 90 \text{ meters}$

Introduction:

Overview of Process

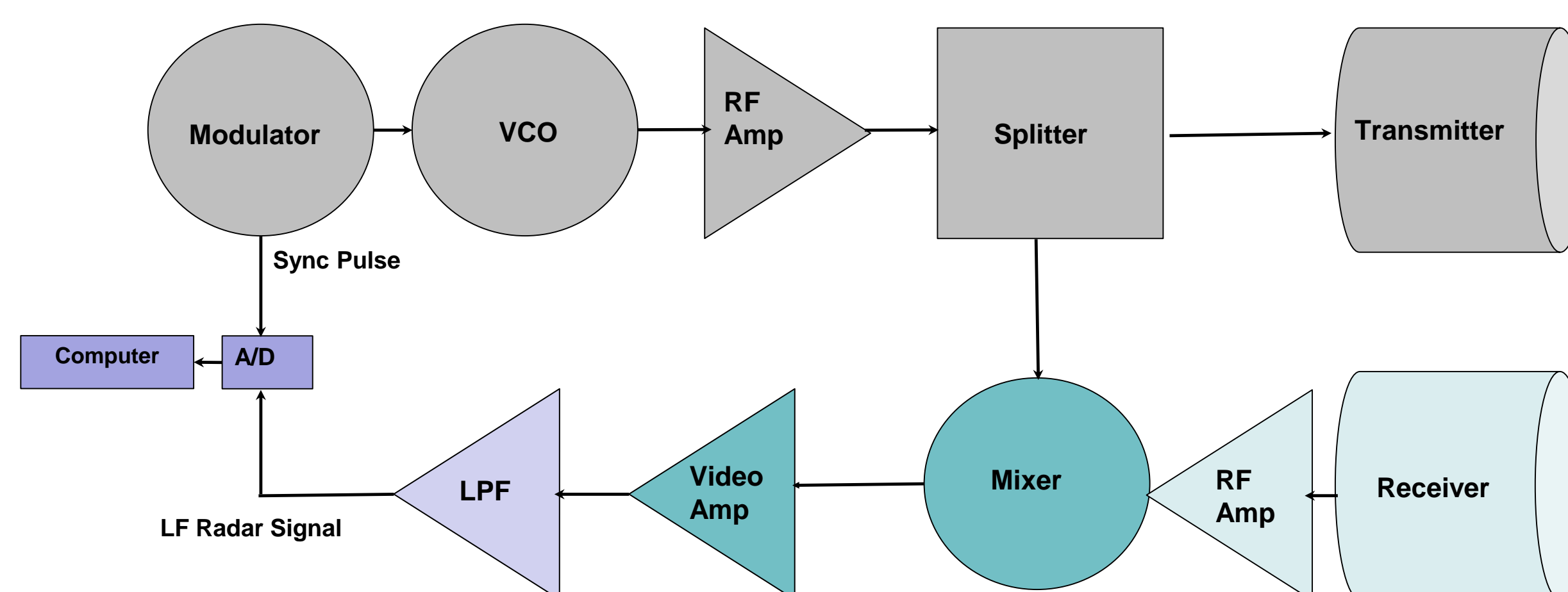


Design Goal: Determine the range and velocity of target

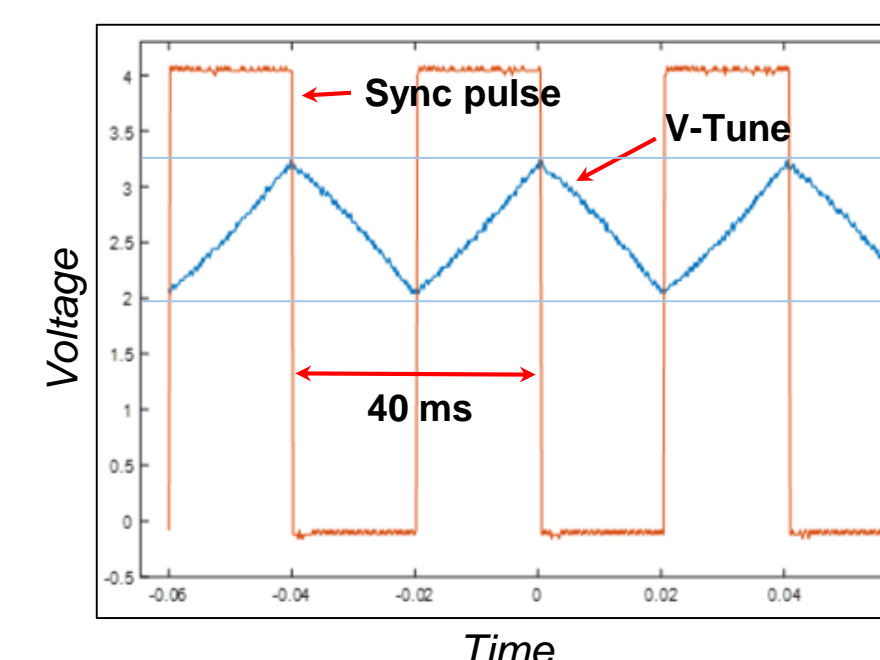
Design Goals:

- Key Characteristics:**
- 2.4 GHz ISM Band
 - Bandwidth 100 MHz
 - Transmit Power < 20 mW
 - Monopole Antennas
 - AA Battery Power Supply
 - Cost Under \$500

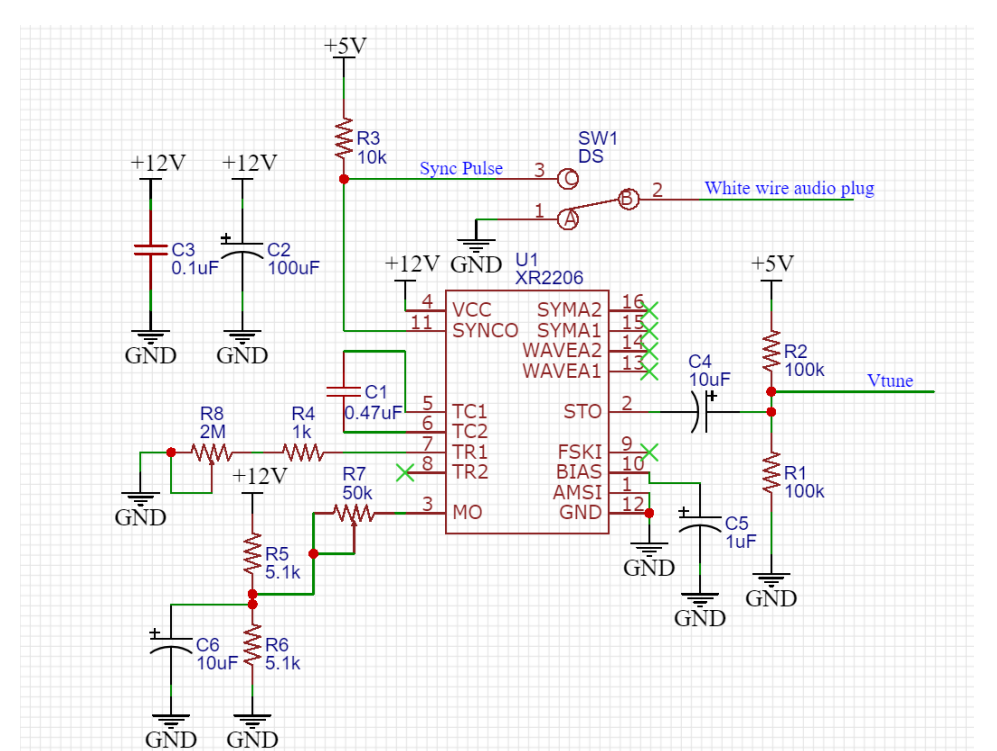
Block Diagram of System



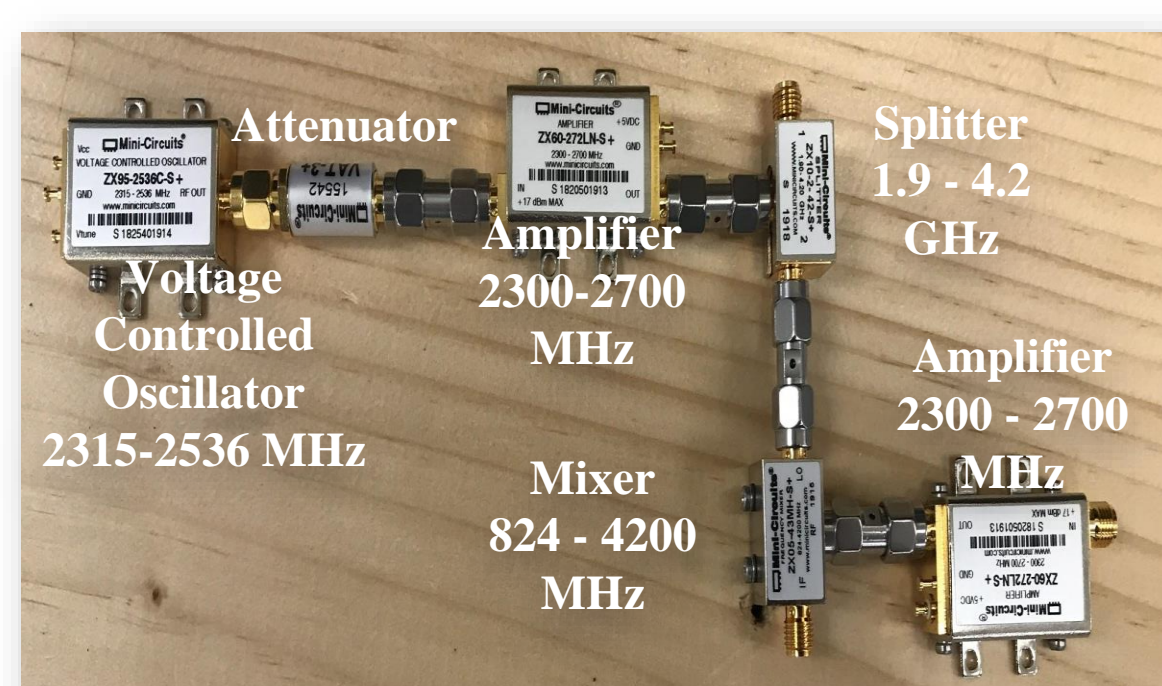
Modulator



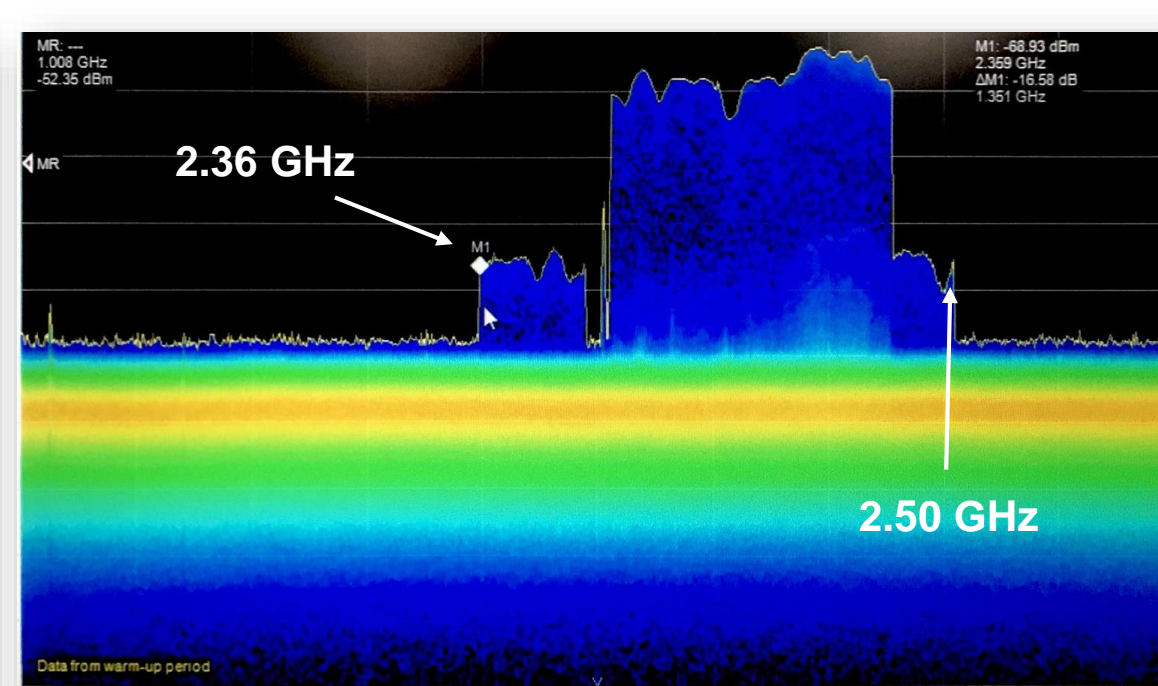
Modulator Circuit



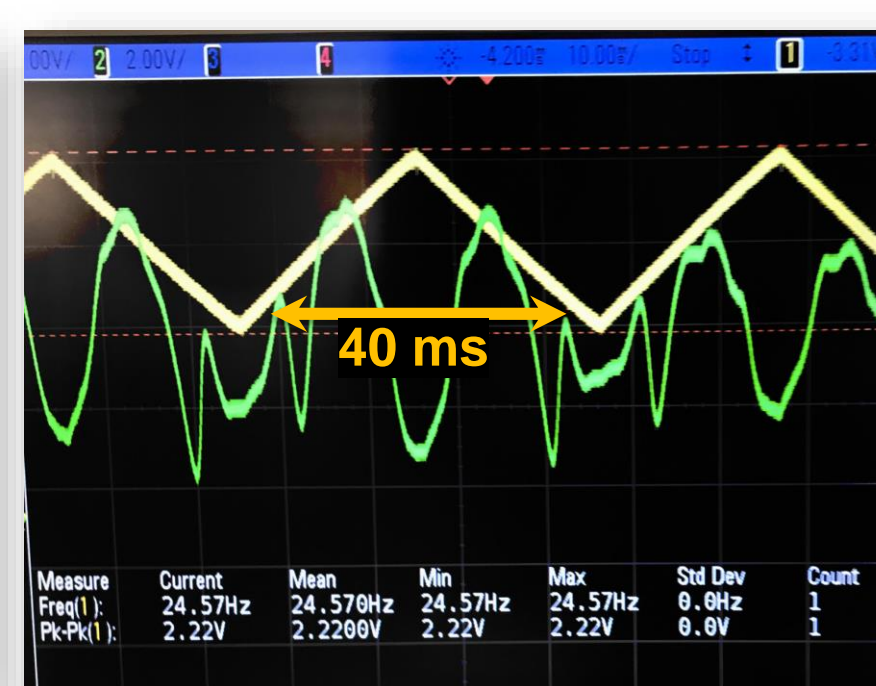
Key Components



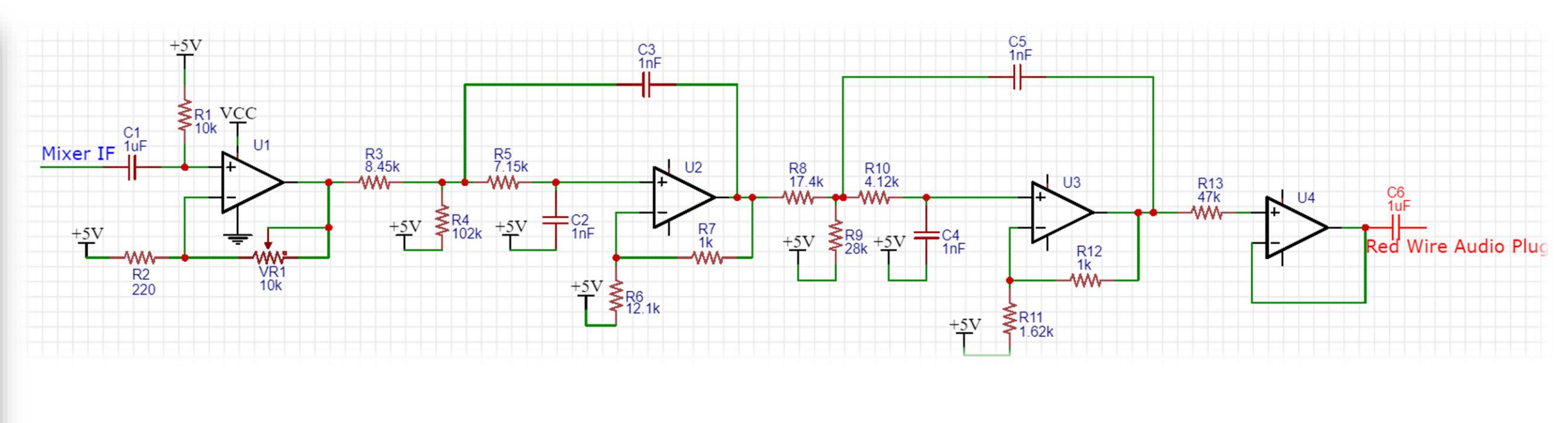
Spectrum



Video Amp. Output



Video Amplifier



Testing and Results:

- RF power meter verified transmit power was under 20 mW
- BW was measured to be approx. 100 MHz
- .wav files were collected in Audacity® for Range and Doppler
- .wav files provided Range and Doppler information in MATLAB
- Doppler live streaming produced results within expected values
- Detected targets with a dynamic range of over 200 meters.

Future Work:

- Implement Synthetic Aperture Radar (SAR)
- Incorporate chaotic oscillator in place of V-tune
- Conduct shakedown testing of Range streaming
- Replace Proto Board with Printed Circuit Board
- Test radar system when system is in motion and target is stationary

Conclusions:

- System demonstrates key radar principles. (LFM, CW, RF Electronics...etc.)
- Signal processing (MATLAB) of raw waveforms yields Range and Doppler information from .wav files and in real time.
- The radar system was built under budget approximate \$300.

Acknowledgements:

- Professor Pappu & Dr. Silva
- Professor Hedrick
- Enrique Haro, Queensborough CC